

ON ACTIVE LOADING OF A BAR MADE OF A MATERIAL WITH DELAYING YIELD IN THE CASE OF A NONLINEAR HARDENING DIAGRAM

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On the basis of the model proposed by V. S. Lenskii, an exact solution is obtained for the problem concerned with propagation of nonlinear elastic-plastic loading waves in a semiinfinite bar with delaying yield.

In [1] a model was proposed which, on the basis of a linear hardening diagram, describes the effect of yield delay of a material.

It is possible to generalize this model for a case when the relation $\sigma = \sigma(\epsilon, t)$ is nonlinear. For this the problem of active loading of a semiinfinite bar is reduced to the construction of the corresponding Riemann wave [2].

Let force $\varphi(t)$ act at the end $x = 0$ of a semiinfinite bar $x \geq 0$, the material of which possesses the effect of yield delay. For the sake of being explicit, we assume that the force is tensile. The $\sigma \sim \epsilon \sim l$ relation in any section of the bar is taken in the form

$$\begin{aligned} \sigma &= E\epsilon & (\epsilon < \epsilon_s) \\ \sigma &= E\epsilon_s(t - x/a_0) + \Phi[\epsilon - \epsilon_s(t - x/a_0)] & (\epsilon \geq \epsilon_s), \end{aligned} \tag{1}$$

Here ϵ_s is a decreasing function of time, while the function $\Phi(z)$ satisfies the following conditions:

$$\Phi(0) = 0, \quad 0 < \Phi'(z) \leq E, \quad \Phi''(z) \leq 0. \tag{2}$$

For the strain at the end to be active, the pressure must satisfy the condition [3]

$$\varphi'(t) \geq E\epsilon_s'(t). \tag{3}$$

In the region of elastic deformations (Fig. 1, region 1) the equation of motion has the form

$$\frac{\partial^2 u}{\partial t^2} = a_0^2 \frac{\partial^2 u}{\partial x^2}, \quad a_0^2 = \frac{E}{\rho}. \tag{4}$$

The solution of Eq. (4) for zero initial data is given by the quadrature

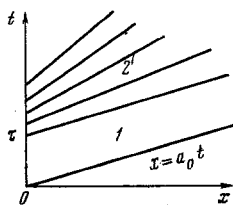


Fig. 1

$$\begin{aligned} u(x, t) &= -\frac{a_0}{E} \int_0^{t-x/a_0} \varphi(\xi) d\xi \\ \epsilon = \frac{\partial u}{\partial x} &= \frac{1}{E} \varphi(t - x/a_0), \quad v = \frac{\partial u}{\partial t} = -\frac{a_0}{E} \varphi(t - x/a_0). \end{aligned} \tag{5}$$

The determination of the stress-strain state inside the elastic-plastic region 2 reduces to finding the solution of the equation

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$$\frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + \frac{a^2 - a_0^2}{a_0} \varepsilon_s' (t - x/a_0), \quad a^2 = \Phi'(\varepsilon - \varepsilon_s) / \rho, \quad a^2(0) = a_0^2 = \frac{E}{\rho} \quad (6)$$

for the following boundary conditions:

$$\sigma(0, t) = \varphi(t), \quad u_1 = u_2 \quad \text{for } x = a_0(t - \tau). \quad (7)$$

Here τ is the instant at which plastic strains occur at the end of the bar.

It is easy to show that the characteristic $x = a_0(t - \tau)$ is a line of weak discontinuity. There the last condition (7) can be replaced by the stipulation of continuity of velocities and strains for $x = a_0(t - \tau)$.

We introduce into the analysis a new function $U(x, t)$, given by the equation

$$U(x, t) = u(x, t) + a_0 \int_{\tau}^{t-x/a_0} \varepsilon_s(\xi) d\xi \quad (8)$$

$$\varepsilon^* = \frac{\partial U}{\partial x} = \varepsilon - \varepsilon_s(t - x/a_0), \quad V = \frac{\partial U}{\partial t} = v + a_0 \varepsilon_s(t - x/a_0).$$

Then Eq. (6) assumes the form

$$\frac{\partial^2 U}{\partial t^2} = a^2(\varepsilon^*) \frac{\partial^2 U}{\partial x^2} \quad (9)$$

The function $U(x, t)$ here must satisfy the following conditions:

$$\varepsilon^*|_{x=0} = \varepsilon_0^*(t), \quad \varepsilon^* = V = 0 \quad \text{for } x = a_0(t - \tau) \quad (10)$$

where $\varepsilon_0^*(t)$ is a given function of time.

Equation (9) constitutes a quasi-linear equation of the hyperbolic type, which is equivalent to the following system of characteristics:

$$dx = \pm a(\varepsilon^*) dt, \quad dV = \pm a(\varepsilon^*) d\varepsilon^*. \quad (11)$$

The last conditions (11) can be integrated along the corresponding characteristics in the xt plane

$$V = \pm \int_0^{\varepsilon^*} a(\xi) d\xi + c_{1,2} \quad (12)$$

where the constants c_1 and c_2 have, generally speaking, have different values on different characteristics.

We show that in the region 2 the integral of Eq. (9) exists,

$$V = - \int_0^{\varepsilon^*} a(\xi) d\xi. \quad (13)$$

Indeed, along the characteristics of negative slope the relation

$$V = - \int_0^{\varepsilon^*} a(\xi) d\xi + c_2$$

holds.

Since the characteristics of negative slope intersect the line $x = a_0(t - \tau)$ on which $\varepsilon^* = V = 0$, then $c_2 \equiv 0$. Thus the integral (13) exists in the region 2.

The characteristics of positive slope are straight lines. Indeed, from the existence of the integral (13) and the characteristic condition

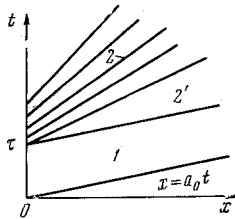


Fig. 2

Here t_0 is any point on the t axis for which, in accordance with the boundary condition (10), the force $\varphi(t_0)$ or, which is the same thing, $\varepsilon_0^*(t)$ is known.

The solution of the problem in the region 2 is obtained in the form of the Riemann wave [2]

$$\varepsilon^* = \varepsilon_0^*(t - x/a(\varepsilon^*)), \quad V = - \int_0^{\varepsilon^*} a(\xi) d\xi. \quad (15)$$

The strains and velocities of sections of the bar are expressed by the following equations:

$$\begin{aligned} \varepsilon &= \varepsilon_0^*(t - x/a(\varepsilon - \varepsilon_s)) + \varepsilon_s(t - x/a_0) \\ v &= - \int_0^{\varepsilon - \varepsilon_s} a(\xi) d\xi - a_0 \varepsilon_s(t - x/a_0). \end{aligned} \quad (16)$$

In particular, if the function $\Phi(z)$ is linear,

$$\Phi(z) = E_1 z \quad (E_1 < E)$$

then the solution (16) is transformed into the well-known solution for plastic regions given in [1]. From the solution thus obtained we see that elastic relaxation waves, arising as a result of spontaneous reduction of the yield point of the material with time, are imposed on the plastic loading waves in the region 2.

If $\Phi'(0) \neq E$, then a region of pure relaxation of stresses (the region 2' in Fig. 2) appears between the regions 1 and 2, i.e., in this region the solution has the form

$$\varepsilon = \varepsilon_s(t - x/a_0), \quad v = - a_0 \varepsilon_s(t - x/a_0). \quad (17)$$

In the region 2 in this case the solution (16) remains valid.

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